



Michigan Connected and Automated Vehicle Working Group

July 23, 2019



Meeting Packet

1. Agenda
2. Meeting Notes
3. Attendance List
4. Presentations

Michigan Connected and Automated Vehicle

Working Group



July 23, 2019

NextEnergy

461 Burroughs Street, Detroit, MI 48202

Meeting Agenda

12:30 PM Registration and Networking

1:00 PM

Introduction and Update

Valerie Sathe Brugeman, Assistant Director, CAR

Next Energy Welcome Remarks

Jim Saber, President and CEO, Engineering & Advanced Technology, NextEnergy

AV Regulation Update

Catherine Barrett, Chief Legal Counsel, United States Senator Gary Peters

**An Introduction to the International Alliance for Mobility Testing and Standardization:
A Global Approach to Testing Advanced Mobility Systems and Services**

John Tintinalli, Director of Innovation, SAE International

PlanetM - Global Mobility Events and Technology Activations

Kathryn Snorrason, Director of Strategic Accounts, PlanetM

2:20 PM Networking Break

2:40 PM Hot Topics Discussion

Frank Perry, Principal Consultant, CAV Program Manager, WSP

Update on MDOT CAV Activities

Elise Feldpausch, Connected Vehicle Specialist, Michigan Department of Transportation

HD Maps: Key Enabler of Autonomous Driving

Praveen Chandrasekar, Senior Product Manager, Autonomous Driving, TomTom

Electric Vehicle Strategy at Consumers Energy

Scott Weber, Director of Alternative Energy Solutions, Consumers Energy

4:00 PM Meeting Adjourned

Michigan Connected and Automated Vehicle Working Group

July 23, 2019



Meeting Notes

The Summer 2019 meeting of the Michigan Connected and Automated Vehicle Working Group was held on July 23, 2019, and hosted by NextEnergy located at 461 Burroughs Street, Detroit, MI 48202.

Valerie Sathe Brugeman, Assistant Director of Transportation Systems Analysis, CAR welcomed the Michigan CAV Working Group attendees, reviewed the meeting agenda and mentioned noteworthy CAV (and related) news.

Jim Saber, President and CEO, Engineering & Advanced Technology, NextEnergy, also welcomed all attendees to NextEnergy. Mr. Saber highlighted NextEnergy's initiatives related to cleaner energy, vehicle infrastructure, and partnership opportunities in Detroit and Michigan.

Catherine Barrett, Chief Legal Counsel, United States Senator Gary Peters, participated remotely and provided an update on federal automated vehicle (AV) regulations. Ms. Barrett talked about the goal of federal AV regulations, which is to advance new technologies, improve safety, and mobility. House and Senate committees are working closely to develop a bipartisan bill that can be incorporated into the new transportation bill scheduled for discussion next year.

John Tintinalli, Director of Innovation, SAE International, presented "An Introduction to the International Alliance for Mobility Testing and Standardization (IAMTS): A Global Approach to Testing Advanced Mobility Systems and Services." IAMTS is a global, membership-based association of stakeholders focused on the testing, standardization, and certification of advanced mobility systems and services. IAMTS' mission is to join testing consumers and providers at a global scale to help develop a commonly accepted framework of test scenarios, validation and certification methods, and terminology. Another goal is to develop and grow an international portfolio of advanced mobility testbeds and service providers that meet the highest quality implementation and operational standards. CAR is a core member of IAMTS and will lead North America engagement efforts for IAMTS.

Kathryn Snorrason, Director of Strategic Accounts, PlanetM, presented "PlanetM - Global Mobility Events and Technology Activations." The purpose of the PlanetM Platform is to strengthen Michigan's position as the center for global mobility by leveraging assets, companies, and technology. It has made more than 3,400 company connections and created more than 200 jobs. Upcoming events include CAR MBS, PlanetM Mobility Meetup, and LA Automobility in California. Ms. Snorrason also gave a summary on activities related to Mobility Grant Pilots, Israel Innovation Grant, and 2020 NAIAS Michigan Mobility Challenge.

After the networking break, **Frank Perry, Principal Consultant, CAV Program Manager, WSP**, continued the meeting with the Hot Topics Discussions. Mr. Perry discussed two topics: 1) Provider Service Identifiers (PSID) and Service Specific Permissions (SSP); and 2) OmniAir & USDOT Map Tool Updates. PSID is a hexadecimal value assigned to CV messages and services and needs to be consistent across deployments for interoperability. SSPs provides an additional level of “permissions” within a message or service. OmniAir is developing testing cases for DSRC, C-V2X, and ETSI testing standards, while the U.S. DOT map tool are in beta testing.

Elise Feldpausch, Connected Vehicle Specialist, Michigan Department of Transportation, provided an update on MDOT’s statewide CAV activities, including Security Credentials Management System (SCMS) procurement status, Central Signal Control System project, and TerraForm Manager system. Ms. Feldpausch indicated that MDOT is continuously evaluating its CAV activities and strategically moving forward in order to balance and maximize investment outcomes, considering the rapid evolution of new technologies.

Praveen Chandrasekar, Senior Product Manager, Autonomous Driving, TomTom, presented “HD Maps: Key Enabler of Autonomous Driving.” Mr. Chandrasekar highlighted how automated vehicles see beyond the range of sensors and the role of HD maps in automated driving, followed by examples of HD map lane models, map delivery methods, as well as updating and maintenance requirements and approaches.

Scott Weber, Director of Alternative Energy Solutions, Consumers Energy, spoke about electric vehicle strategies at Consumers Energy. Mr. Weber indicated that Consumers Energy started a new era for renewable energy in Michigan with approval of its Clean Energy Plan in 2019. The “Power MI Drive” includes a three-year program to make it easier for electric vehicles (EV) owners to charge their EVs, and to ensure the electric grid is prepared to capture the benefits from the growing EV market. Specific options for consumers include enhanced website options and other electrification support.

The meeting adjourned at 4:00.

MDOT maintains a webpage dedicated to its work related to CAV technologies (http://www.michigan.gov/mdot/0,1607,7-151-9621_11041_38217--,00.html). The page includes documents, presentations, and other materials that may be of interest to CAV stakeholders. Meeting packets containing materials (agenda, meeting notes, attendance, and presentation slides) from past Michigan Connected and Automated Vehicle Working Group meetings are also available on this page.

Michigan Connected and Automated Vehicle Working Group

July 23, 2019



Attendance List

| First | Last | Organization |
|----------|-------------|------------------------------|
| Al | Lecz | Washtenaw Community College |
| Anthony | Magnan | Verizon Wireless |
| Barb | Land | Square One Education Network |
| Ben | Miners | IMS |
| Bert | Baker | Great Wall Motors |
| Bill | Shreck | MDOT |
| Christyn | Lucas | Detroit Regional Chamber |
| Corri | Wofford | Senator Gary Peters |
| Cyrilla | Menon | Danlaw |
| Daniel | Lindenmeyer | ON Semiconductor |
| Edwin | Marples | CAR |
| Elise | Feldpausch | MDOT |
| Eric | Gannaway | Siemens Mobility |
| Frank | Perry | WSP |
| Frank | Sgambati | Robert Bosch LLC |
| Gary | Streelman | Magneti Marelli |

| First | Last | Organization |
|-----------------|---------------------|--|
| Heidi | Pfannes | Albert Kahn Associates |
| Heinz | Mattern | Visteon |
| Howard | Abbey | SBD Automotive |
| Jason | Rouse | Sekisui |
| Jenya | Abramovich | SEMCOG |
| Jim | Ohlinger | PPG |
| Jim | Saber | NextEnergy |
| John | Tintinalli | SAE International |
| Joseph | Gorman | CAV Engineer |
| Karista | Gallick | WIN |
| Kathryn | Snorrason | PlanetM |
| Kellie | Treppa | ON Semiconductor |
| Kevin | Taylor | IEEE |
| Kristie | Pfosi | Mitsubishi Electric Automotive America |
| Madhu | Posani | RIDE Technologies |
| Mahendra | Muli | dSPACE Inc |
| Marc | Rosenmayr | Motherson Innovations |
| Mark | Peters | Qualcomm |
| Matt | Bell | SBD Automotive |
| Mike | Miller | Orion Measurement Solutions |
| Richard | Murphy | Michigan Municipal League |
| Nelson | Kelly | Macomb Community College |
| Prajakta | Pimple | Mercedes-Benz Research & Development, NA |
| Praveen | Chandrasekar | TomTom |

| First | Last | Organization |
|-------------|--------------|--|
| Qiang | Hong | CAR |
| Rachel | Jones | The Road Commission For Oakland County |
| Ross | Sanders | Lawrence Technological University |
| Savan | Adeshra | Kettering University |
| Scott | Hotz | Southwest Research Institute |
| Scott | Weber | Consumer Energy |
| Sean | Kelley | mannik smith group |
| Stephen | Selander | Miller Canfield |
| Steven | Litz | Powerlink Systems |
| Ted | Sadler | Integral Blue |
| Terrence | Hicks | Metro Strategies, Inc. |
| Terry | Croad | City of Southfield |
| Terry | Woychowski | LINK Engineering |
| Thomas | Doran | Hubjects |
| Tom | Richer | MDOT |
| Tony | Gioutsos | Siemens |
| Valerie | Brugeman | CAR |
| WAYNE | SNYDER | NextEnergy Center |
| William | Tansil | Life is Great |
| Yogesh Tony | Hadrine | Kettering University |
| Zahra | Bahrani Fard | CAR |

Michigan Connected and Automated Vehicle Working Group



Presentations



Michigan Connected and Automated Vehicle Working Group

Valerie Sathe Brugeman, Assistant Director, CAR

July 23, 2019

NextEnergy, Detroit

Meeting Agenda

1:00 PM

Introductions and Update

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Next Energy Welcome Remarks

Jim Saber, President and CEO, NextEnergy

AV Regulation Update

Catherine Barrett, Chief Legal Counsel, U.S. Senator Gary Peters

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John Tintinalli, Director of Innovation, SAE International

PlanetM - Global Mobility Events & Technology Activations

Kathryn Snorrason, Director of Strategic Accounts, PlanetM

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Networking Break

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Electric Vehicle Strategy at Consumers Energy

Scott Weber, Director of Alternative Energy Solutions, Consumers Energy

4:00 PM

Meeting Adjourned

Tour of NextEnergy

Working Group Mission



Cooperatively pursue projects and other activities that are best accomplished through partnerships between multiple agencies, companies, universities, and other organizations and that ultimately advance Michigan's leadership position in connected and automated vehicle research, deployment, and operations.

Goals

- Benefit our state and our industry (automotive and more)
- Enhance safety and mobility in Michigan and beyond



Upcoming CAV Events

- **SAE CyberAuto Challenge**
July 21-26, 2019 | Warren, MI
- **CAR Management Briefing Seminars**
August 6-8, 2019 | Traverse City, MI
- **Autonomous Vehicles Detroit 2019**
August 21-23, 2019 | Novi, MI
- **The Battery Show**
September 10-12, 2019 | Novi, CA
- **Automated Bus Consortium**
September 12, 2019 | Detroit, MI
- **Others?**

Thank you to our
hosts!

CENTER FOR AUTOMOTIVE RESEARCH



PURE MOBILITY



planet M

In spring 2016, the PlanetM **brand** was born to represent collective mobility efforts and assets across the state.

Michigan. Where big ideas in mobility are born.

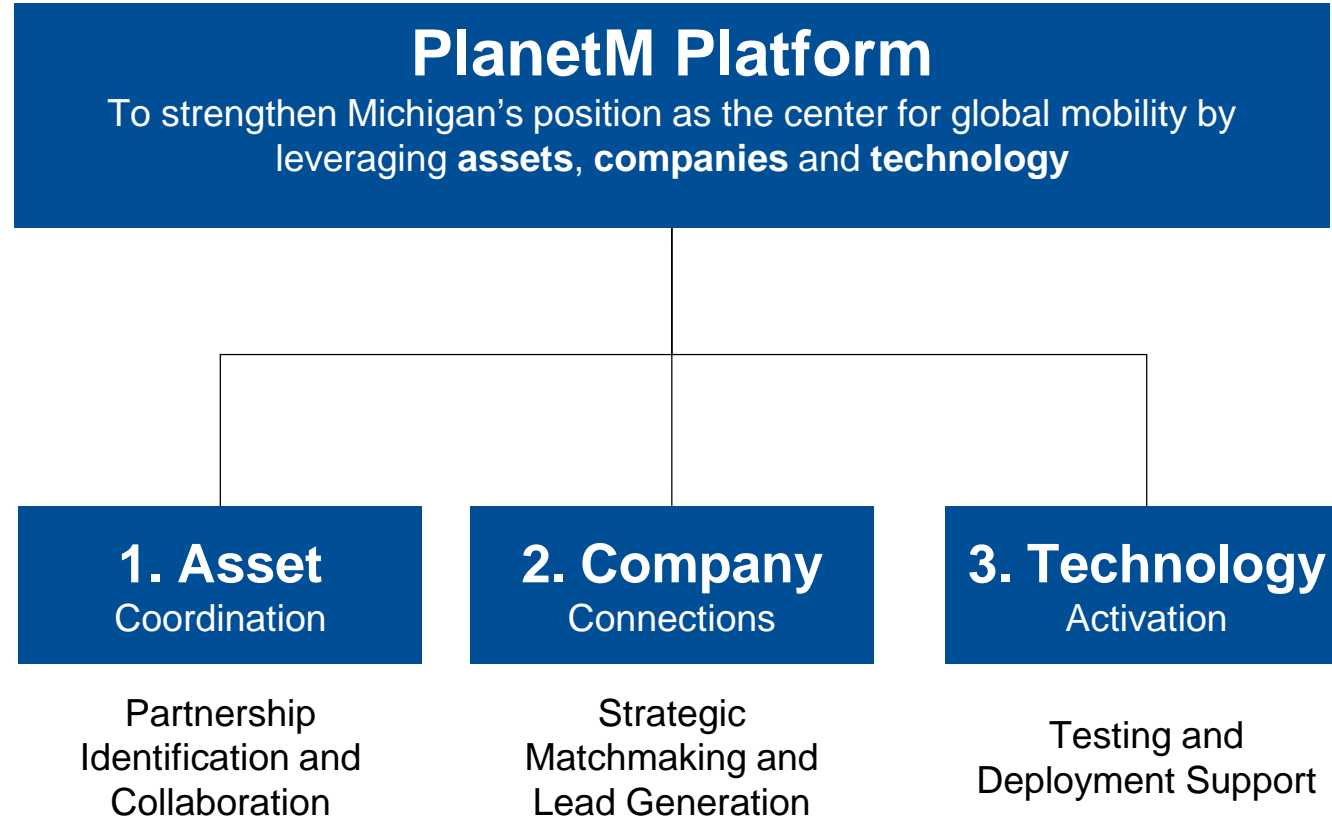
A year later, the State built on the early success of PlanetM by growing beyond its awareness-focused advertising campaign into a full-service statewide **business development** program.

Michigan. Leading the transportation revolution.

Today, we do **three things**.



THREE CORE BUSINESS DEVELOPMENT OFFERINGS



45,000,000

Facilitated Revenue

37

Technology Activations*

200+

Jobs

3,400+

Company Connections

**37 technology activations by the end of 2019*

COMPANY CONNECTIONS

**ECOMOTION
(ISRAEL)**

Date: June 11, 2019

Objective: Launch the Israel-Michigan startup grant and facilitate meetings between local Israeli startups and Automotive Corporate Partners/Investors

Attendees*: 3,800+ attendees from 44 countries, 1800 companies, 135 exhibiting startups

Match Meetings: 46 Meetings were held between startups and technology seekers

**Approximately 400 people stopped by the PlanetM booth.*

**HARDWARE TECH SUMMIT
(DETROIT)**

Date: June 19, 2019

Objective: Highlight and further strengthen Michigan as a global leader in designing, building, and deploying innovative products

Attendees: 350+

Match Meetings: 200+ Meetings were held between startups, accelerators, manufacturers and corporate automakers

**TECHCRUNCH MOBILITY
(CALIFORNIA)**

Date: July 10, 2019

Objective: Innovation Break for 20 minutes on the main stage and a one hour Breakout Session in the afternoon

Attendees: 800+ at the conference and 85 attendees at the Breakout Session

 **UPCOMING EVENTS**

**CAR MBS
(MICHIGAN)**

Date: August 6-8, 2019

Objective: Sponsoring Techstars startups to attend CAR MBS, hosting match meetings at CAR MBS and hosting a networking reception at 20 Fathoms

Request: If you plan on attending CAR MBS, you will receive an invite to participate in match meetings to meet mobility startups

**PLANETM MOBILITY MEETUP
(MICHIGAN)**

Date: August 12, 2019

Objective: Designed to bring together dynamic startups in the automotive technology space with Michigan's automotive and mobility industry stakeholders to help create a cohesive and robust ecosystem to connect, share and collaborate

Request: Visit <https://www.planetmlandingzone.com/mobility-meetup-august> and register

**LA AUTOMOBILITY
(CALIFORNIA)**

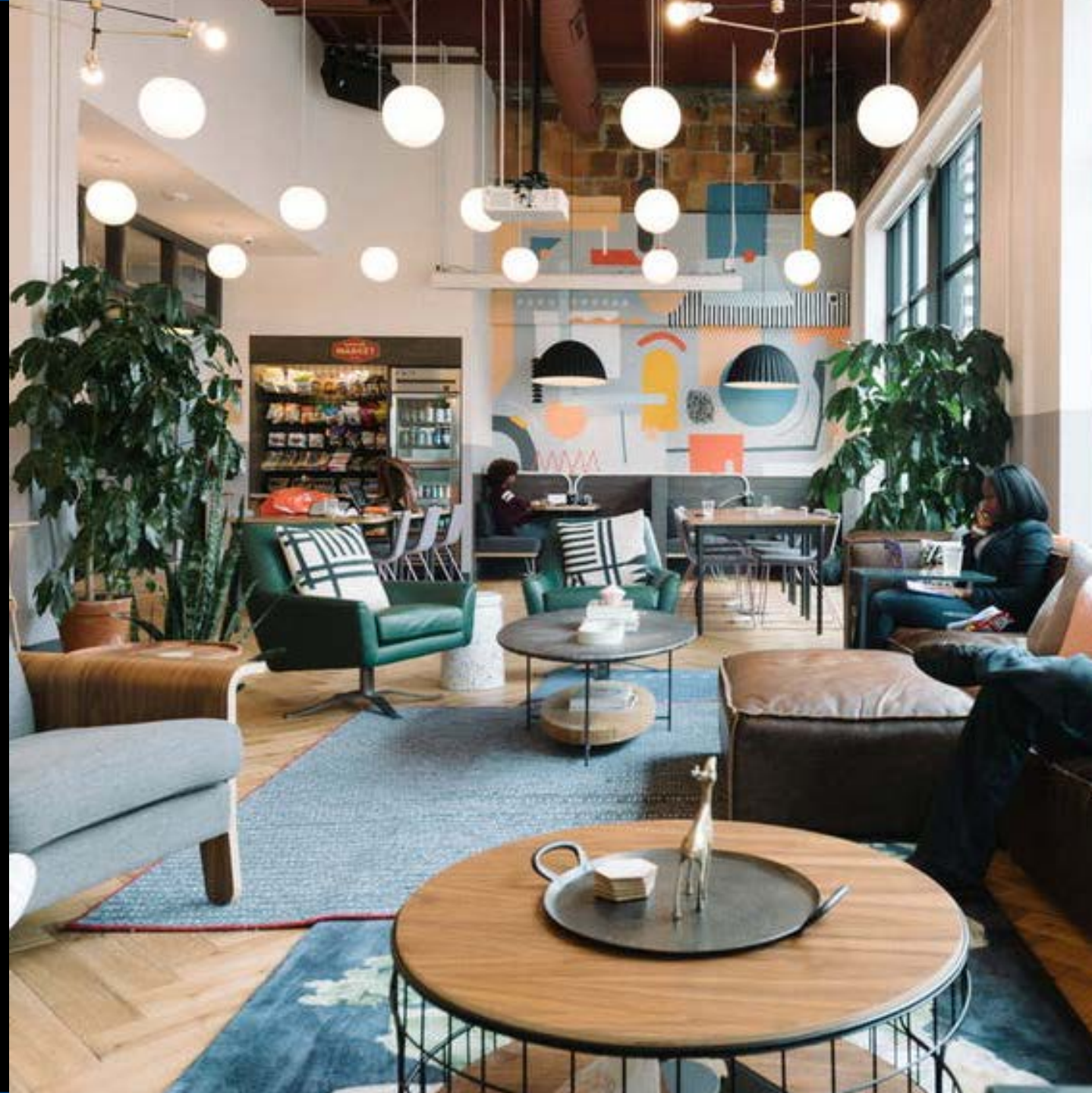
Date: November 19, 2019

Objective: Facilitate one-on-one match meetings between corporates (OEMs, Tier 1s, Investors) and mobility startups

Request: If you plan on attending LA Automobility, you will receive an invite to participate in match meetings to meet mobility startups



PLANETM LANDING ZONE





TECHNOLOGY ACTIVATION

Grants | Challenges | City Pilots

PLANETM MOBILITY GRANT

\$1.9M in grant funding to encourage mobility companies to deploy their technologies in Michigan or test at Michigan's state-of-the-art facilities

Kettering
UNIVERSITY

Michigan
Technological
University


American Center
for Mobility

M | city
UNIVERSITY OF MICHIGAN


Michigan UAS
Michigan Unmanned Aerial Systems Consortium

ISRAEL INNOVATION GRANT

New partnership with Israel Innovation Authority (IIA) to test and deploy new technologies in Michigan

 רשות החדשנות
Israel Innovation
Authority

planetM MOBILITY GRANT PILOTS

ROUND 1

Ann Arbor

Bus driver alerts for predicting vulnerable road user actions

HUMANISING
AUTONOMY

Grand Rapids

First-ever digital alerts between fire, police & EMS



HAAS ALERT

Detroit

Road condition evaluation & early crack detection



RoadBotics

Detroit

AI intersection safety



ROUND 2

Detroit

AV paratransit shuttle at DMC with local community

NAVYA

SE Michigan

Software-based GPS testing that could significantly reduce costs in AVs

NAVENTIK

Royal Oak

Automated delivery inside hospital



Battle Creek

Secure RX delivery in rural area w/underutilized vans



Rochester

AV shuttle at OU as part of STEM program



NAIAS 2020 MICHIGAN MOBILITY CHALLENGE

Overview: Deploy level 3+ shuttle demonstrations during NAIAS 2020, 1. Airport to downtown and 2. Downtown circulator

Workshop: June 17, 2019

RFP: RFP due July 29, 2019

App Provider: Moovit

Partners: Governor's Office, MEDC/PlanetM, MDOT

CITY:ONE MICHIGAN CENTRAL STATION CHALLENGE*

Overview: An invitation for Detroit residents to design, plan and pilot new solutions to improve mobility surrounding the Michigan Central Station

Pilots: \$250,000 will be awarded to up to 5 teams to pilot their ideas

Partners: Ford, City of Detroit, MEDC/PlanetM

**Formerly known as the City of Tomorrow Challenge.*

AUTOMATED BUS CONSORTIUM

Overview: Joint procurement of up to 100 automated, electric buses. Will select two locations in Michigan (between GR, MSU and Huron County)

Summit: September 12, 2019

Partners: MEDC/PlanetM, MDOT, AECOM and a dozen transportation agencies across the US

PROJECT KINETIC

- **MicroTransit:** Dynamically routed buses
- **Car4You:** Low-income car-sharing
- **ParkDetroit:** Perks, reservations program
- **ChargeD:** EV education in public spaces
- **Busority:** Signal priority for public transit
- **CTI:** Hub that sources infrastructure data



ANN ARBOR MOBILITY TRANSFORMATION PROGRAM

- Enhanced simulation that will allow for scenario-planning to understand the use and impact of new and emerging mobility modes.
- Autonomous shuttle in downtown AA or at UM hospital





International Alliance for Mobility Testing and Standardization
A Program of SAE ITC

Impact of transformation towards a smart mobility ecosystem



Redesign of urban cores to support smart mobility



Source: Toyota

Develop new smart mobility ecosystems

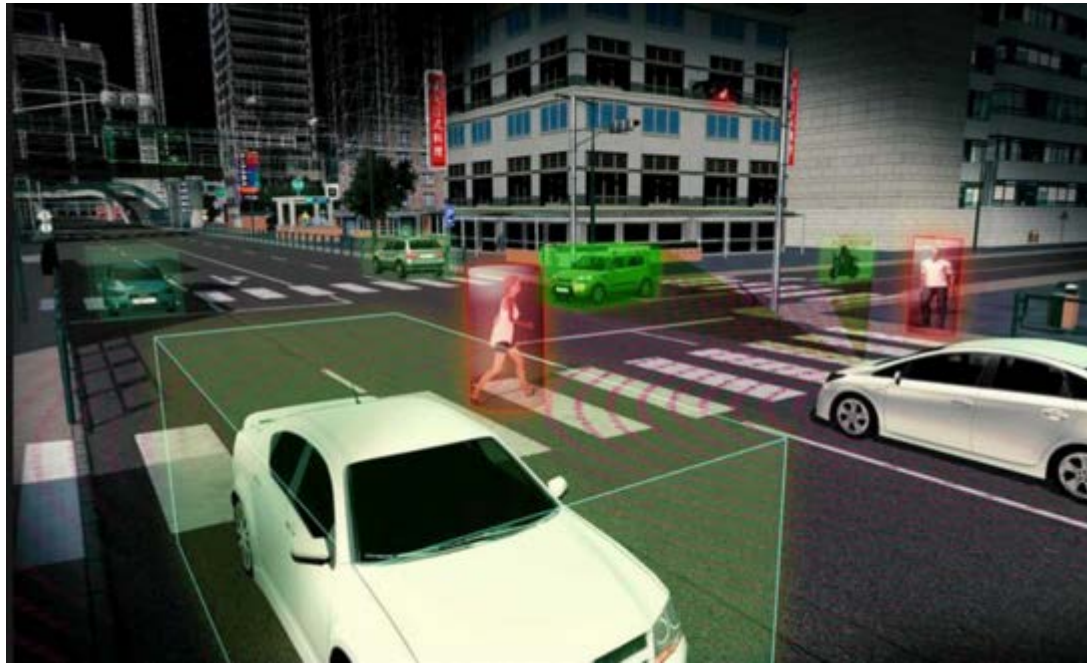


Rethink V2X infrastructure development for large scale CV/AV/EV adoption



An important driver of the transformation will be the implementation of new international standards and regulations for CV/AV/EV mobility solutions which are both vehicle and infrastructure based

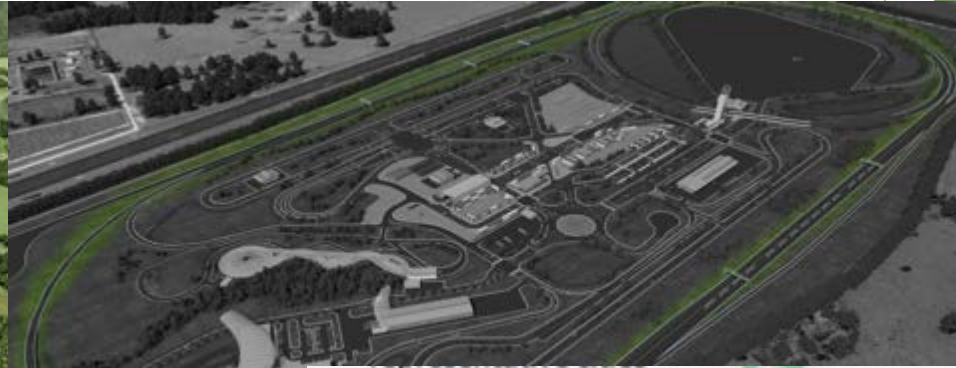
Testing in Virtual Environments, Open Environments



Growing AV test facilities worldwide



BMW, Czech Republic



Suntrax, Florida



ZALA ZONE, Hungary



NICE CITY, Shanghai

Problems IAMTS Aims to Solve

- ▶ Growing complexity of potential risks and testing needs
- ▶ No measuring stick for what tests should be conducted and how they should be conducted
- ▶ Lack of global harmonization of standards, regulations and approaches regarding testing
- ▶ Need to match rapidly evolving technologies with a process for creating standards that is equally rapid and flexible
- ▶ Difficulty with comparability and replicability of tests across facilities, geographies and physical/virtual boundaries
- ▶ Issues with test data portability and compatibility
- ▶ Validating simulation fidelity
- ▶ Optimizing simulation and physical testing



Scope

A global, membership-based association of organizations that are stakeholders in the testing, standardization and certification of advanced mobility systems and services.



Mission

Bring together testing consumers and providers at a global scale to help develop a commonly accepted framework of test scenarios, validation and certification methods, and terminology.

To develop and grow an international portfolio of advanced mobility testbeds and service providers that meet the highest quality implementation and operational standards.



Vision

Create a global community comprised of advanced mobility testing service providers and companies, organizations and agencies in need of such services.

Learn, develop and share best-practices to ensure consistent, replicable and reliable testing.

Maintain a global directory of physical, virtual and cyber-physical testbeds and support and promote their audited capabilities.

Promote the rapid evolution of globally harmonized standards and certifications to ensure reliable deployment of advanced mobility systems and services.

Example Domains

- ▶ ADS (Automated Driving System) Testing
- ▶ V2X Communication, particularly in complex environments
- ▶ Vehicle and infrastructure cybersecurity
- ▶ Multi-modal testing (e.g., air-ground)
- ▶ Multi-system staging and testing (e.g., urban street with rideshare, bike share, electric scooter, L4 shuttles and human drivers)
- ▶ Dynamic wireless charging
- ▶ Automated or remote-controlled ground control systems

Organizational Structure

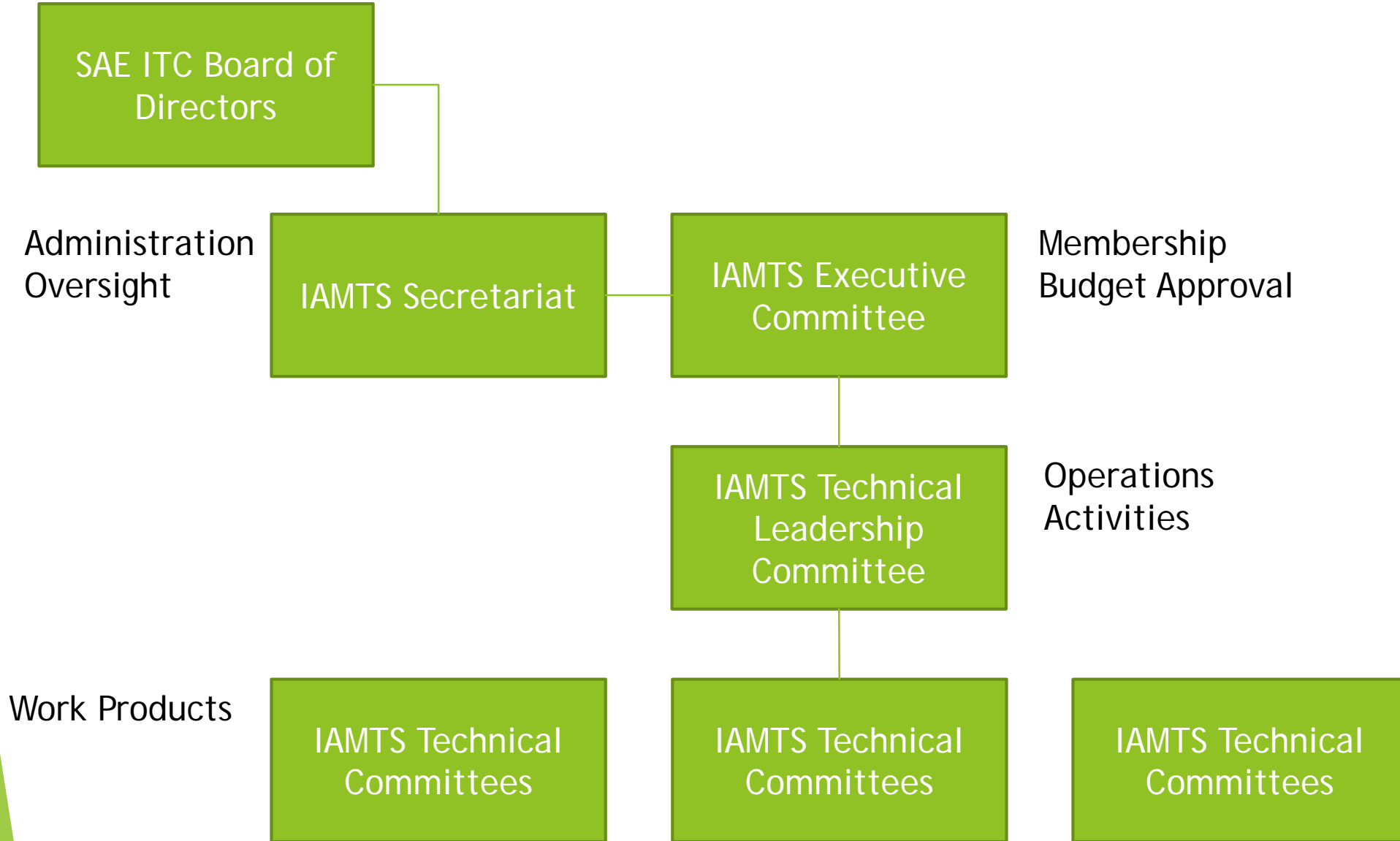
The background of the slide is white with abstract green geometric shapes on the right side. These shapes include overlapping triangles and polygons in various shades of green, from light lime to dark forest green. A thin, light gray line also extends from the bottom right towards the center of the slide.

Corporate Structure

IAMTS is established as a program under SAE Industry Technologies Consortia (“SAE ITC”). SAE ITC is a 501(c)(6) non-for-profit trade association that enables new or existing consortia programs to successfully impact their industry through widespread adoption of industry practices or procedures.

IAMTS is made up for member organizations which are engaged in the smart mobility ecosystem. IAMTS offers memberships to both public and private, large and small organizations.

Governance



| | Membership Level | | | | | |
|---|--|--|---|--|--|--|
| | Strategic Partner | Strategic Member | Core Member | Basic Member | Affiliate Member | Expert |
| Regulation, Standards and Certification Providers | <ul style="list-style-type: none"> Non-Profit SDO | <ul style="list-style-type: none"> SDO CTO | <ul style="list-style-type: none"> SDO CTO Government | <ul style="list-style-type: none"> SDO Small CTO | <ul style="list-style-type: none"> Government Small Non-Profit | |
| Testing Service Providers | | <ul style="list-style-type: none"> Academic Insurer RECS | <ul style="list-style-type: none"> Test Facility Operator Simulator RECS ICT Academic Government | <ul style="list-style-type: none"> Test Facility Operator Simulator Small RECS SmB* | <ul style="list-style-type: none"> Academic Government Small Non-Profit | <ul style="list-style-type: none"> SmB* |
| Testing Service Consumers | | <ul style="list-style-type: none"> Manufacturer Insurer MaaS RECS ICT | <ul style="list-style-type: none"> Manufacturer Insurer MaaS RECS ICT Academic Government | <ul style="list-style-type: none"> MaaS RECS ICT SmB | <ul style="list-style-type: none"> Academic Government Small Non-Profit | <ul style="list-style-type: none"> SmB |
| Other | | <ul style="list-style-type: none"> Other** | <ul style="list-style-type: none"> Other** | <ul style="list-style-type: none"> Other** | | |

SDO =Standards Development Organization
CTO = Certification & Testing Organization
RECS = Research, Engineering and Consulting Services firm
ICT = Information and Communications Technology firm
MaaS = Mobility as a Service Provider
SmB = Small Business / Startup
Manufacturer = OEM or Tier 1-2 Supplier
Academic = Non-Profit Academic or Academic-Affiliated Research Institution
Operator = Testbed Operator or Test Operator
Government = Local, National, Regional and Regulatory
Other = Other organization whose products, services or interests are relevant to the IAMTS mission, vision and scope

*Must be vetted by IAMTS
**Must have Executive Committee approval

Current Members



CENTER FOR
AUTOMOTIVE
RESEARCH

ANICE CITY

国家智能网联汽车(上海)试点示范区
National Intelligent Connected Vehicle (Shanghai) Pilot Zone



Key Objectives

- ▶ Provide an audited directory of shared use mobility testbeds and simulation providers worldwide
- ▶ Aggregate lessons-learned, and when possible anonymized data, to identify critical scenarios and best practices for testing those scenarios
- ▶ Educate members and learn together to achieve common goals
- ▶ Provide shared services to testbeds to alleviate their overhead
- ▶ Publish research, opinions, and white papers
- ▶ Participate in the development of specifications and standards through appropriate bodies
- ▶ Advocate for members
- ▶ Advocate for voluntary or regulatory adoption of testing standards

Example Activities, Services and Benefits Provided by and for the IAMTS Community and External Clients



| Membership Service | Examples |
|--------------------|---|
| Training | <ul style="list-style-type: none">- AV verification & validation methods- Mobility related rules & regulations |
| Consulting | <ul style="list-style-type: none">- Testbed design- Cybersecurity |
| Data | <ul style="list-style-type: none">- Access to shared database- Analytics services |
| Testing | <ul style="list-style-type: none">- Test operations |
| Certification | <ul style="list-style-type: none">- Vehicles and systems- Test facilities, training, and methodologies |
| R&D Projects | <ul style="list-style-type: none">- Best Practice Determination |

Organizational Roadmap

Phase 1 - Q4/2018-Q1/2019

Approval of membership model and fee structure by sponsoring entities

Identification of and consultation with founding member candidates

Identification of strategic testbeds

Phase 2 - Q2/2019-Q4/2019

Commitment of founding members

Implementation of governance structure

Initiate first projects

Building of membership base and service portfolio

Phase 3 - Q1/2020

Strategic review of implementation phase and membership feedback

Growth of membership portfolio

Optimization of membership service portfolio to ensure sustainable operation

First Deliverable

DIN-SAE Spec 91381:

*Terms and Definitions Related to Testing of Automated
Vehicle Technologies*

Upcoming Activities

August 5-6, Tianjin China

- Executive Committee Meetings and Technical Committee Meetings
- Establish Detailed Roadmap of Activities
- Host: CATARC

September 16, Munich Germany:

- Automated Vehicle Testing Symposium Europe
- Host: TÜV SÜD



More Info

Inquire through the Center for Automotive Research (CAR)
or email info@iamts.org

MDOT CAV Working Group Meeting

NextEnergy

July 23, 2019

Frank Perry
Sr. CAV Program
Manager

WSP ¹

Agenda

- Provider Service Identifiers (PSID) and Service Specific Permissions (SSP)
- OmniAir & USDOT Map Tool Updates

PSID & SSP

Provider Service Identifier (PSID)

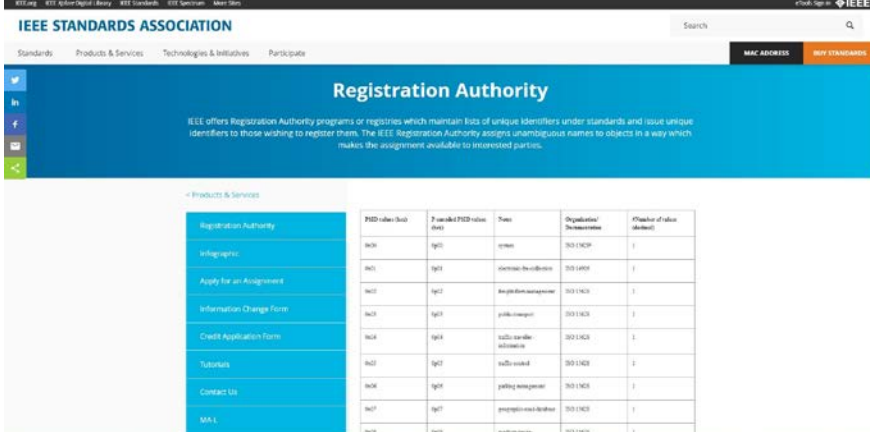
- A Provider Service Identifier (PSID) is hexadecimal value assigned to CV messages and services
- Defined in 1609.3, PSIDs serve two (2) purposes:
 1. Filter messages for receiving applications
 - The lower (stack) layers only deliver relevant messages to applications
 - Ex: prevents a Red Light Violation application (that uses SPaT & Map) from receiving TIM messages
 2. Used in WSAs to announce available services at the roadside and/or back office.

Also, security certificates contain PSIDs which authorizes a device to broadcast specific messages.

Provider Service Identifier (PSID)

- A list of PSIDs and the owning organization is provided in IEEE 1609.12 as well as on IEEE Registration Authority (<https://standards.ieee.org/products-services/regauth/psid/public.html>)

PSID usage need to be consistent across deployments for interoperability



The screenshot shows the IEEE Standards Association Registration Authority website. The page title is "Registration Authority". Below the title, there is a brief description: "IEEE offers Registration Authority programs or registries which maintain lists of unique identifiers under standards and issue unique identifiers to those wishing to register them. The IEEE Registration Authority assigns unambiguous names to objects in a way which makes the assignment available to interested parties." Below this, there is a table with the following columns: "PSID (IEEE Std)", "7 digit IEEE Std", "Name", "Organization/Department", and "Number of values (objects)". The table contains the following data:

| PSID (IEEE Std) | 7 digit IEEE Std | Name | Organization/Department | Number of values (objects) |
|-----------------|------------------|-----------------|-------------------------|----------------------------|
| IEEE 1609.12-01 | 160912 | IEEE 1609.12-01 | IEEE 1609.12-01 | 1 |
| IEEE 1609.12-02 | 160912 | IEEE 1609.12-02 | IEEE 1609.12-02 | 1 |
| IEEE 1609.12-03 | 160912 | IEEE 1609.12-03 | IEEE 1609.12-03 | 1 |
| IEEE 1609.12-04 | 160912 | IEEE 1609.12-04 | IEEE 1609.12-04 | 1 |
| IEEE 1609.12-05 | 160912 | IEEE 1609.12-05 | IEEE 1609.12-05 | 1 |
| IEEE 1609.12-06 | 160912 | IEEE 1609.12-06 | IEEE 1609.12-06 | 1 |
| IEEE 1609.12-07 | 160912 | IEEE 1609.12-07 | IEEE 1609.12-07 | 1 |
| IEEE 1609.12-08 | 160912 | IEEE 1609.12-08 | IEEE 1609.12-08 | 1 |
| IEEE 1609.12-09 | 160912 | IEEE 1609.12-09 | IEEE 1609.12-09 | 1 |
| IEEE 1609.12-10 | 160912 | IEEE 1609.12-10 | IEEE 1609.12-10 | 1 |

Service Specific Permissions(SSP)

- SSPs provides an additional level of “permissions” within a message or service
- Where PSIDs indicate **message** type, SSPs indicate **specific content** within the message
- Signal Request Message (SRM) Example:
 - The same (SAE J7235) Signal Request Message (SRM) (with PSID 0x20-40-96) is utilized to request Priority **and** Preemption.
 - Using just the PSID, any vehicle “authorized” to request priority could also request preemption
 - Clearly we would not want a transit or freight vehicle requesting **preemption**
 - An SSP is used to limit transit and freight vehicle types to only being able to request **priority**.
 - 2 SSP’s recommended for SRM:
 - 1 for only requesting priority (Transit/Freight)
 - 1 for requesting priority or preemption (First Responders)

Service Specific Permissions(SSP)

- As of now SSP values are defined by the system designer (not standardized)
- Some SSPs should be standardized to enable cross (deployment) boarder interoperability
 - SPaT, Map, TIM
- Some SSPs don't necessarily need to be standardized
 - SRM
 - Agencies may not want transit and emergency vehicle SRM interoperability

Security Profiles

- PSIDs and SSP are defined in a “Security Profile” document
- A Security Profile should be developed for each message utilized within the CV system
- USDOT CV Pilots have Security Profiles for BSMs, SPaT, Map, TIM, SRM, and SSM

PSID/SSP

Examples:

RSU Message PSIDs

| Message | PSID | SSP |
|---------|------------|------------|
| SPaT | 0x82 | integer=19 |
| Map | 0x20-40-97 | integer=18 |
| SSM | 0x20-40-95 | integer=30 |
| WSA | 0x87 | None |

OBU Message PSIDs

| Message | PSID | SSP |
|------------------------------|-------------|--|
| General Purpose Vehicle | 0x20 & 0x26 | None <i>Note: 0x20 is BSM and 0x26 is Misbehavior Detection and Reporting</i> |
| Snow Plow SRM | 0x20-40-96 | integer=29 |
| Over-the-Air Firmware Update | 0x20-40-89 | TBD |

Advertised in the WSA

| Service | PSID |
|------------------------------|---------------|
| IPv6 Routing | 0x10-20-40-7E |
| Misbehavior Detection | 0x26 |
| Over-the-Air Firmware Update | 0x20-40-89 |
| Snow Plow SRM | 0x20-40-96 |

SCMS

- Certificates contain PSIDs and SSPs
- SCMS Providers need to know the PSIDs used in your system
- SCMS does not need to know SSP

OmniAir & USDOT

OmniAir

- Developing C-V2X Test Cases
 - Held a C-V2X Certification Workshop in Milpitas CA on June 27 hosted by Bureau Verita, an OmniAir Authorized Test Lab
- Summer Policy Series
 - Truck Platooning: V2X Technology in Action Scheduled for 07/25/19 in DC
- Next plugfest in Málaga Spain hosted at DEKRA, an OmniAir Authorized Test Lab, the week of September 30th
 - will include DSRC, C-V2X, and ETSI Standards testing
- OmniAir and 3M are in discussions to transfer the rights of 3M DSRC "Sniffer" to OmniAir. Draft agreement targeted for end of August (2019)
- 3 Certified RSUs (Danlaw, Siemens, and Intersect)
- 3 Certified OBUs (Danlaw, Commsigna, and Lear)

USDOT

- **Updates to the USDOT Map Tool are in Beta Testing**
 - Includes integration with the CAMP Work Zone (WZ) Mapping Tool
 - Upload of RSM data from CAMP Work Zone Mapping Tool
 - Provides the CV stakeholder community to ability to use both features/tools in one platform.

Q&A

Frank Perry

Frank.perry@wsp.com

734.552.9638

MICHIGAN DEPARTMENT OF TRANSPORTATION



Michigan DOT Statewide CAV Program Update

CAR CAV Working Group 2019 | July 23, 2019

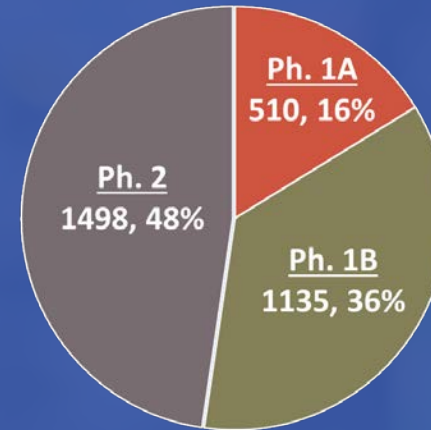


SCMS Procurement

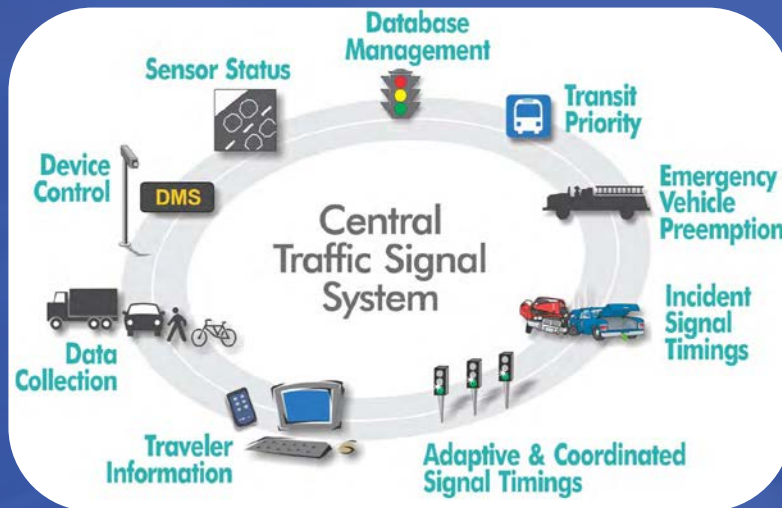
- Final phases of contracting with *Integrity Security Solutions*
- Roll out – Anticipated Sept 2019
- Solution applied to existing and future MDOT deployments

Central Signal Control System

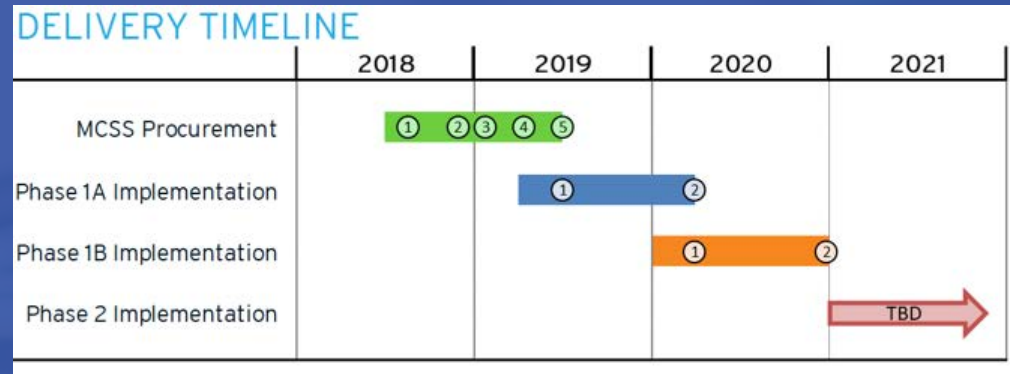
1. Increase the efficiency of Michigan's roadways
 - Provide active and remote traffic signal monitoring
2. Streamline the management of a critical asset
 - Arterial performance (early identification of equipment failures, performance metrics)
3. Prepare for the future of traffic signal management



- Phase 1a - MDOT maintained on TACTICS
- Phase 1b - MDOT maintained not on TACTICS
- Phase 2 - Local agency maintained



Source: DKS



TerraForm Manager

Device Manager

The screenshot displays a map interface with several device icons. A popup window provides the following details for a device:

| 12 Mile at Tech Plaza Dr (Site 321) | |
|-------------------------------------|-----------------------------------|
| Device ID: | 236 |
| Intersection ID: | 1114 |
| Latitude: | 42.507 |
| Longitude: | -83.024 |
| Manufacturer: | Savari |
| Model: | SW-1000 |
| Status: | |
| TIM: | 0 Message(s) EDIT |
| MAP: | Unknown EDIT |
| SPaT: | Unknown |

[MANAGE RSU](#)

TIM Creation

- Defining Data Parameters
 - TIM Description
 - Region Description
 - IDAS Code Time Message
- Content Type
- Frame Type
- Priority
- Geographic Limitations

The screenshot displays the 'TIM Creation' interface. At the top, the breadcrumb navigation reads: 'Device Manager > Dequendre and Stephens Drive > TIMs > Create'. Below this is a satellite map of an urban area with a blue circle highlighting a specific region. The map includes labels for 'Hazel Park Laundromat', 'Track Party Store', 'Malek Restaurant & Meat Market', 'E Woodward Heights Blvd', 'Melville Ave', 'Dequendre Rd', 'Kathleen Ave', and 'Chef Malek'. A form is overlaid on the map, containing the following fields:

- TIM MESSAGE:** Three green buttons labeled 'ROAD-CONSTRUCTION', 'LEFT-LANE', and 'CLOSED'. A checkbox for 'CONVERT ITIS CODES AUTOMATICALLY' is checked.
- CONTENT TYPE:** A dropdown menu with 'Advisory' selected.
- FRAME TYPE:** A dropdown menu with 'Advisory' selected.
- PRIORITY:** A dropdown menu with '3' selected.

At the bottom of the form, there are tabs for 'METADATA', 'CONTENT', 'DATE/TIME', and 'GEO'. An 'ACTIONS' button is located in the bottom right corner of the form area.

BSM and Traffic Signal Controller

The screenshot displays a map interface with several data overlays. On the left, a small table provides timing information:

| | |
|----------------|---------------------|
| Animation Time | 04/26/2019 11:28:15 |
| Vehicle Time | 04/26/2019 11:28:15 |
| Signal Time | 04/26/2019 11:27:57 |

The central 'Vehicle Data' popup contains the following information:

- Vehicle: BSM
- Vehicle Type:
- Time: 04/26/2019 11:28:15
- Latitude: 42.5084748
- Longitude: -83.0468102
- Elevation: 501.6 ft
- Speedometer: 5.19 MPH
- Speed GPS: 0 MPH
- Heading GPS: 179 °
- RPM: 0
- Surface Temp: 0 ° F
- Ambient Temp: 0 ° F
- DewPoint: 0 ° F
- Humidity: 0 %

The right-side 'Signal Information' popup provides details for the intersection:

- Intersection: 12 Mile and Mound
- Latitude: 42.50618281
- Longitude: -83.046343
- Last Received Time: 04/26/2019 11:30:53

At the bottom of the signal information popup, there is a checkbox labeled 'Include in Animation' which is checked.

Traffic Flow Restrictions

- Engineering information vs public relations
- Provide info to Mi Drive and CAV
- Data soon to be incorporated into FHWA WZDx Feed

Transportation Flow Restrictions

LISTING + NEW FILTER

MAP CLOSURE...

JOB ID: 117578

COUNTY: Macomb

DIRECTION: Eastbound

ROAD: I-696

AKA ROAD NAME:

CATEGORY: Triple Lane LANE(S) AFFECTED: Left OPEN LANE(S): Number of Open Lanes TYPE: <Leave Blank> ADDITIONAL INFORMATION: <Leave Blank> LANE SHIFT:

LOCATION: POINT RANGE

START POSITION: TYPE: Cross-Street CROSS-STREET: Mound Rd

END POSITION: TYPE: Cross-Street CROSS-STREET: M-3 (Gratiot)

JOB TYPE: Construction

RESTRICTION START: 04/20/2019 07:00am

RESTRICTION END: 05/24/2019 02:00am

| DAILY CLOSURE TIMES | MON | TUE | WED | THU |
|---------------------|---------|---------|---------|---------|
| | All Day | All Day | All Day | All Day |
| | N/A | N/A | N/A | N/A |

Set daily closure times for all days that do not have a set time to: ALL DAY NONE

DETOUR: Detour field disabled for categories other than total.

ADDITIONAL INFO URL: URL (starting with http:// or https://)

CONTACT INFO: I-696 Project 248-387-8696

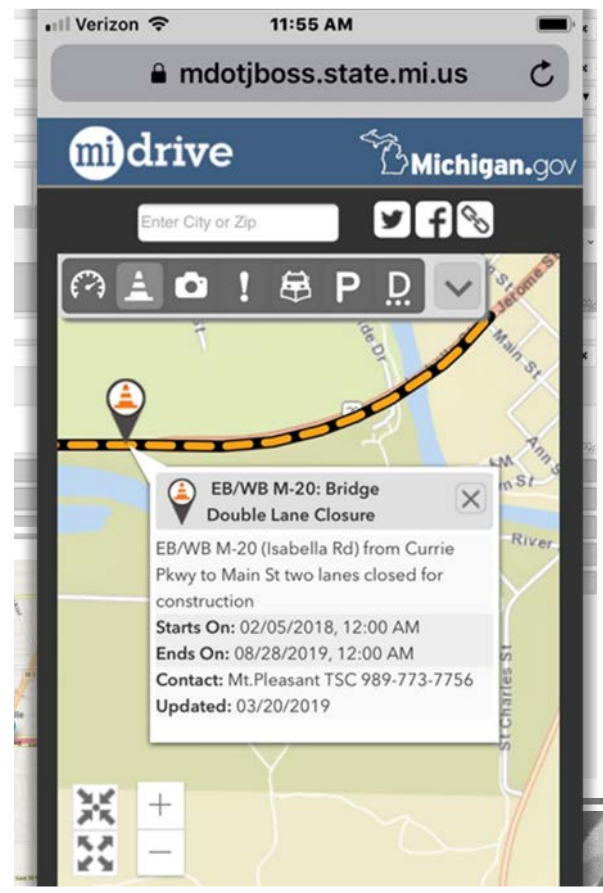
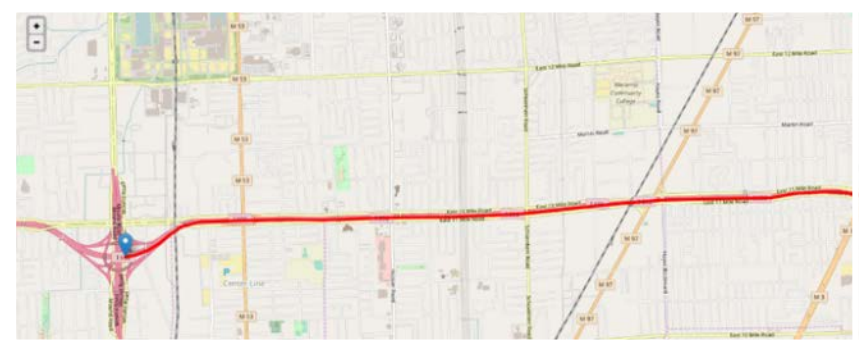
HOLIDAYS: PARTICIPATES IN TRAFFIC SAFETY HOLIDAY

RESTRICTIONS: CLOSURE HAS DIMENSION RESTRICTIONS (WEIGHT, HEIGHT, ETC.)

NOTES:

CREATED BY: zabein

CREATED ON: 04/12/2019 7:08am



Communications

Talent

Research

Infrastructure

Applications


Data

Vehicles



Michigan is Open for Business for CV Partnership Opportunities

HD MAPS: KEY ENABLER OF AUTONOMOUS DRIVING



Praveen Chandrasekar, Senior Product Manager

TomTom AD PU

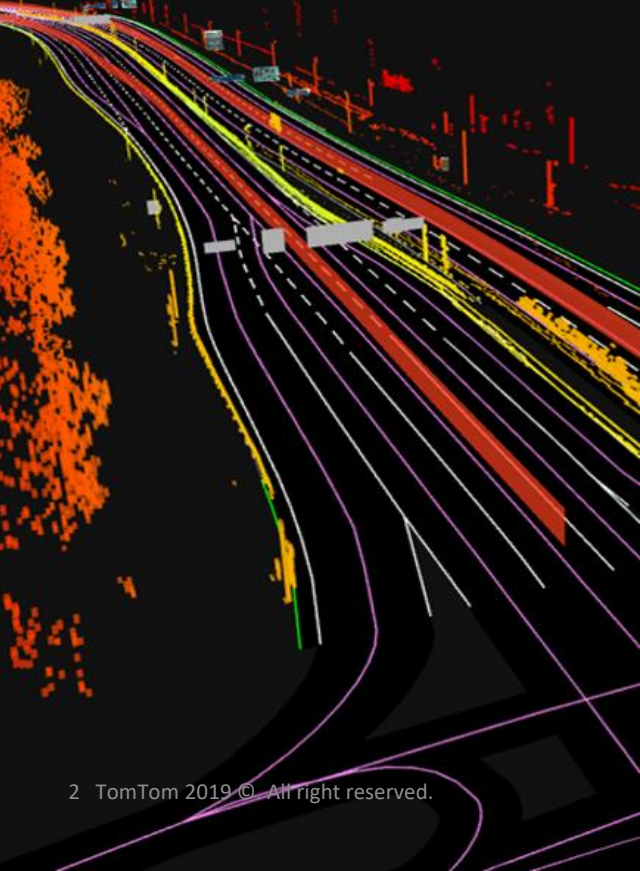
July 2019



TOMTOM 

The Key Pillars of Automated Driving

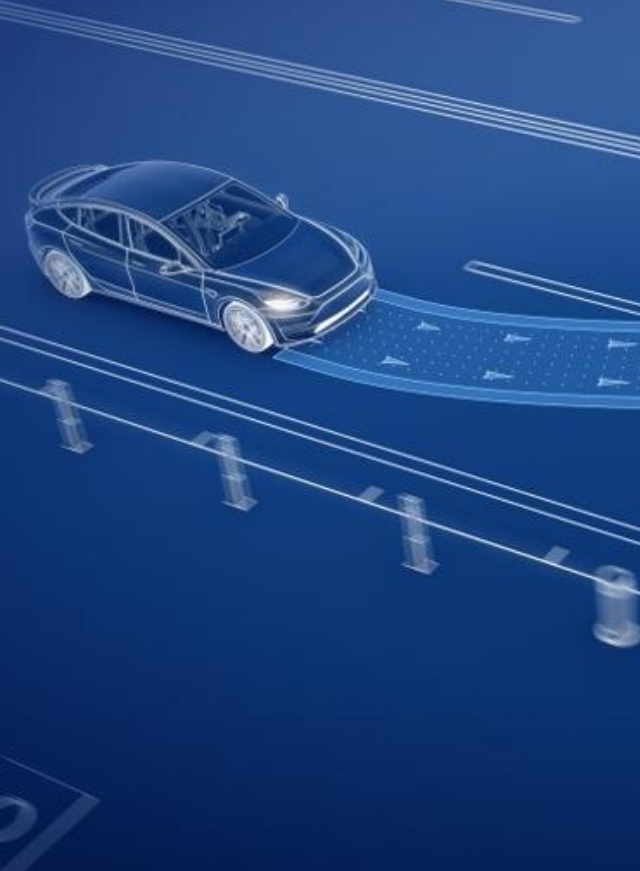
Mapping



Sensing



Driving policy

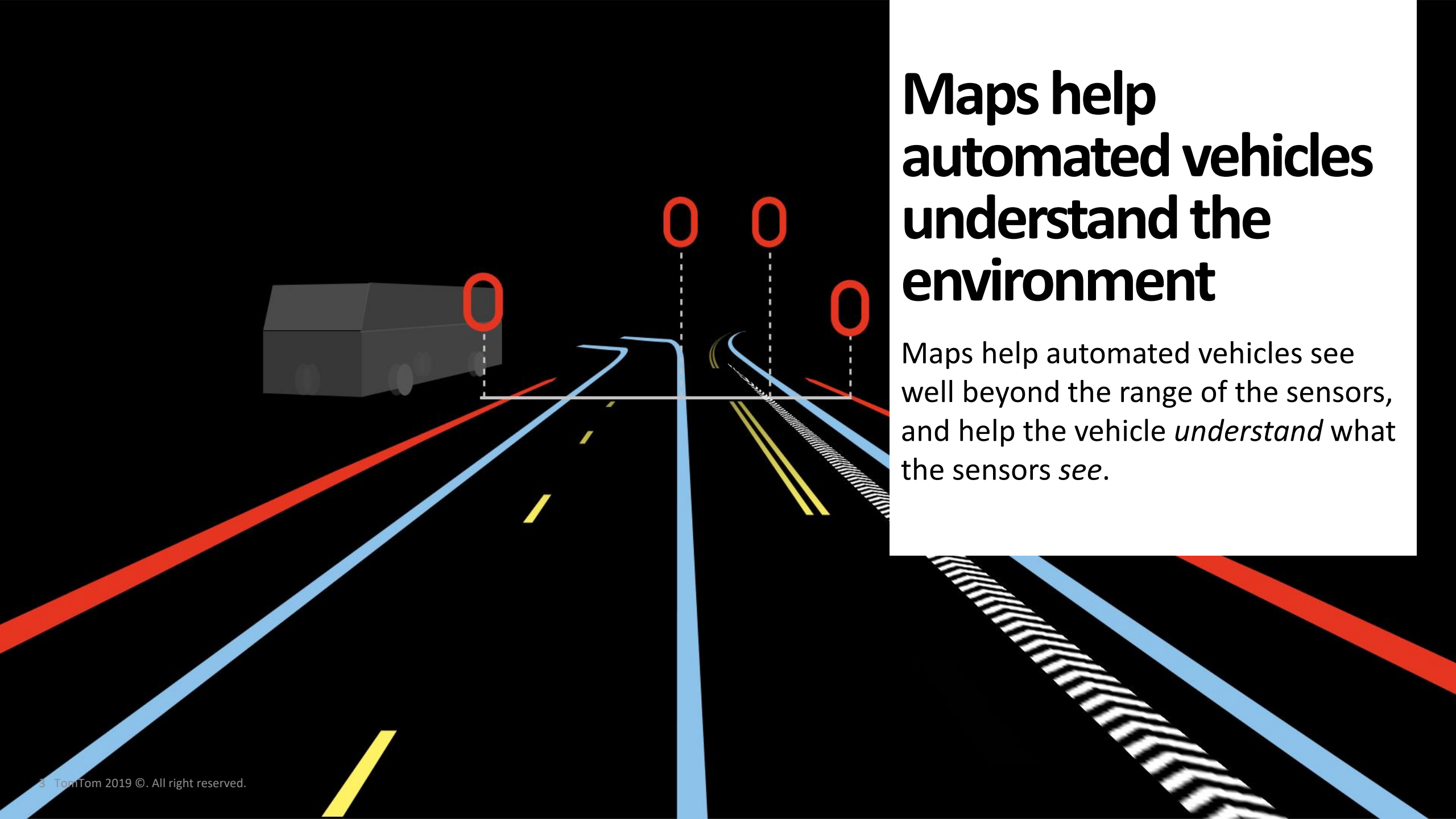


Actuators



Maps help automated vehicles understand the environment

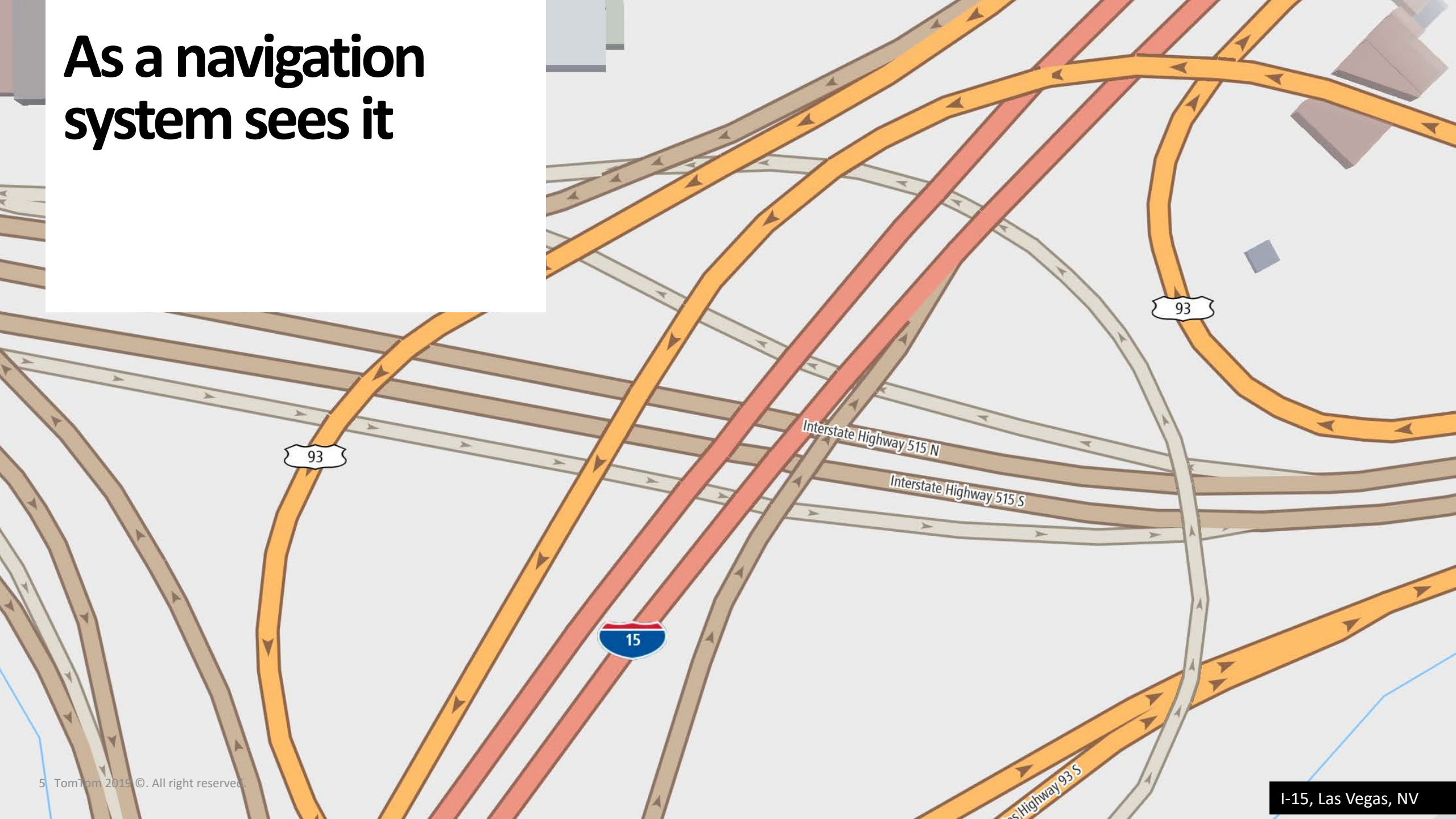
Maps help automated vehicles see well beyond the range of the sensors, and help the vehicle *understand* what the sensors see.



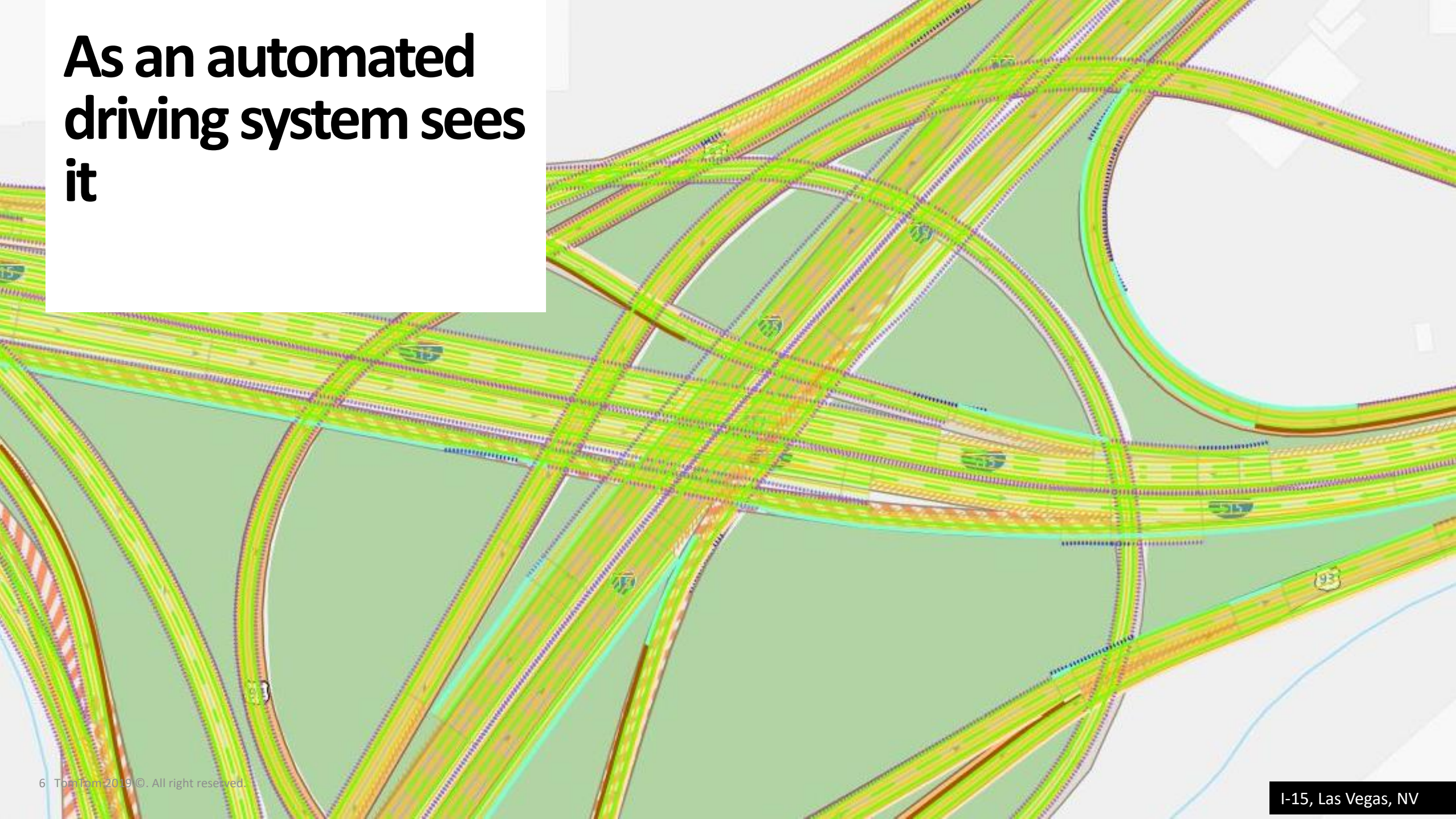
The road as we see it



As a navigation system sees it



**As an automated
driving system sees
it**



The role of HD Maps in automated driving

Localization



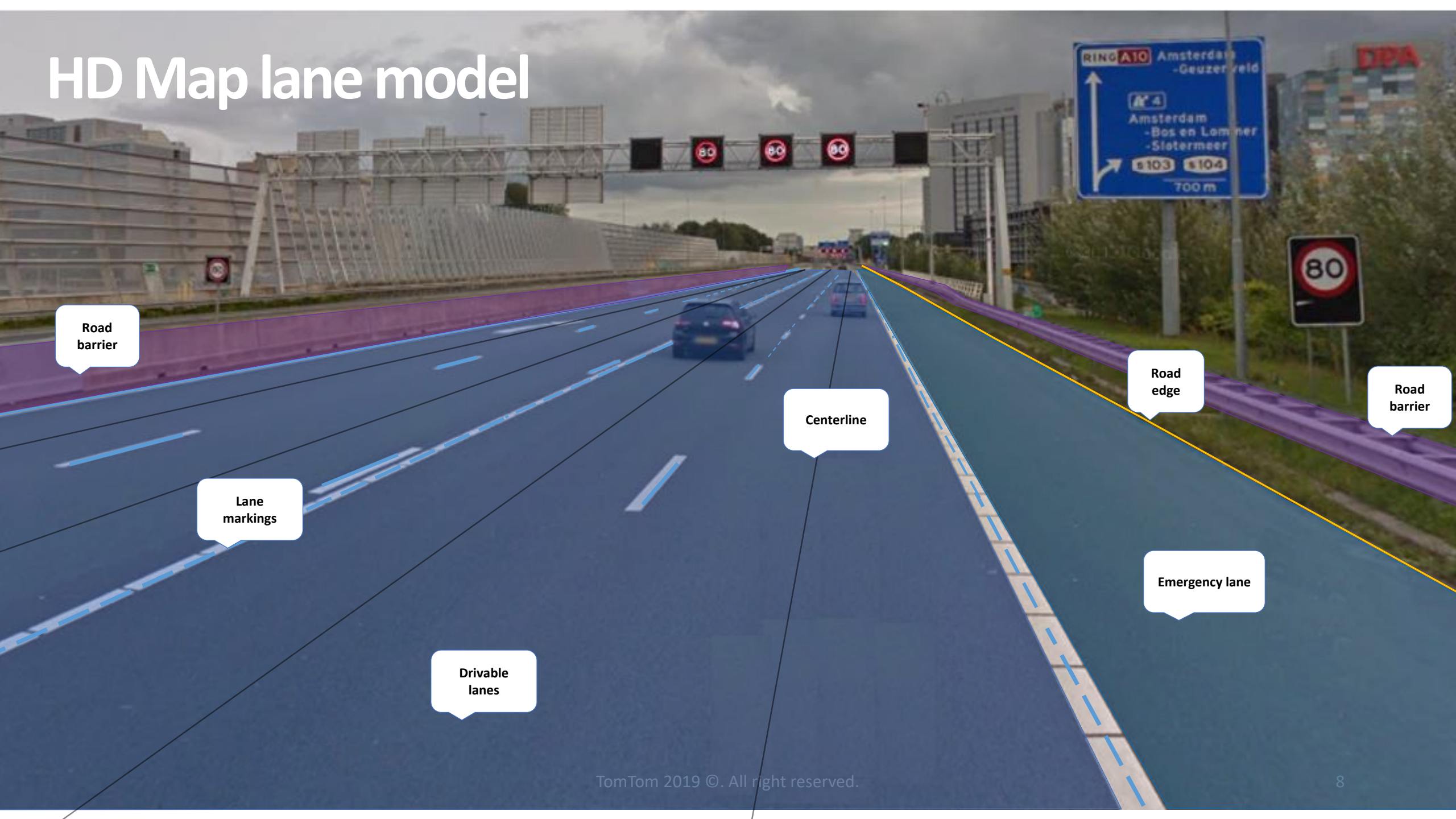
Perception



Path planning



HD Map lane model



Road barrier

Lane markings

Drivable lanes

Centerline

Road edge

Emergency lane

Road barrier

RoadDNA

Additional localization layers



SIGNS



ROADSIDE



POLES



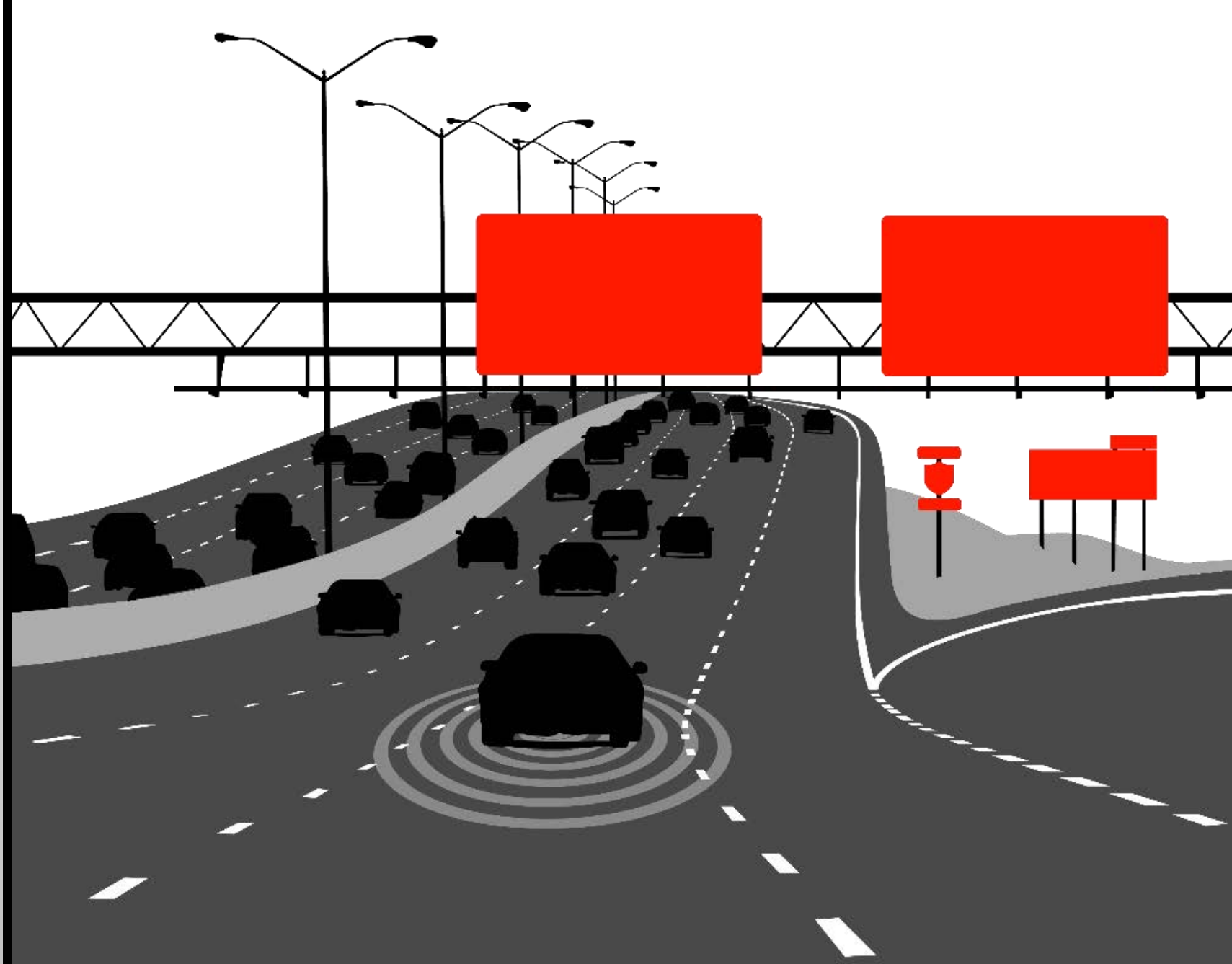
MARKINGS



REFLECTIVITY



RADAR



MOBILE MAPPING

VELODYNE LIDAR COLLECTS
700,000 DATA POINTS
PER SECOND DELIVERING AN ACCURACY TO
WITHIN 2 CM



2 SICK LIDARS
SUPPLEMENT VELODYNE
ENSURING COMPLETE
**CAPTURING OF
ROAD SURFACE
& FURNITURE**



INTERNAL COMPUTER
PROCESSES
1 TERABYTE
OF DATA DAILY



THE LADYBUG 5 COLLECTS
**3.8 BILLION
PIXELS PER KM**
THAT ARE USED TO VALIDATE
REAL-WORLD CHANGES



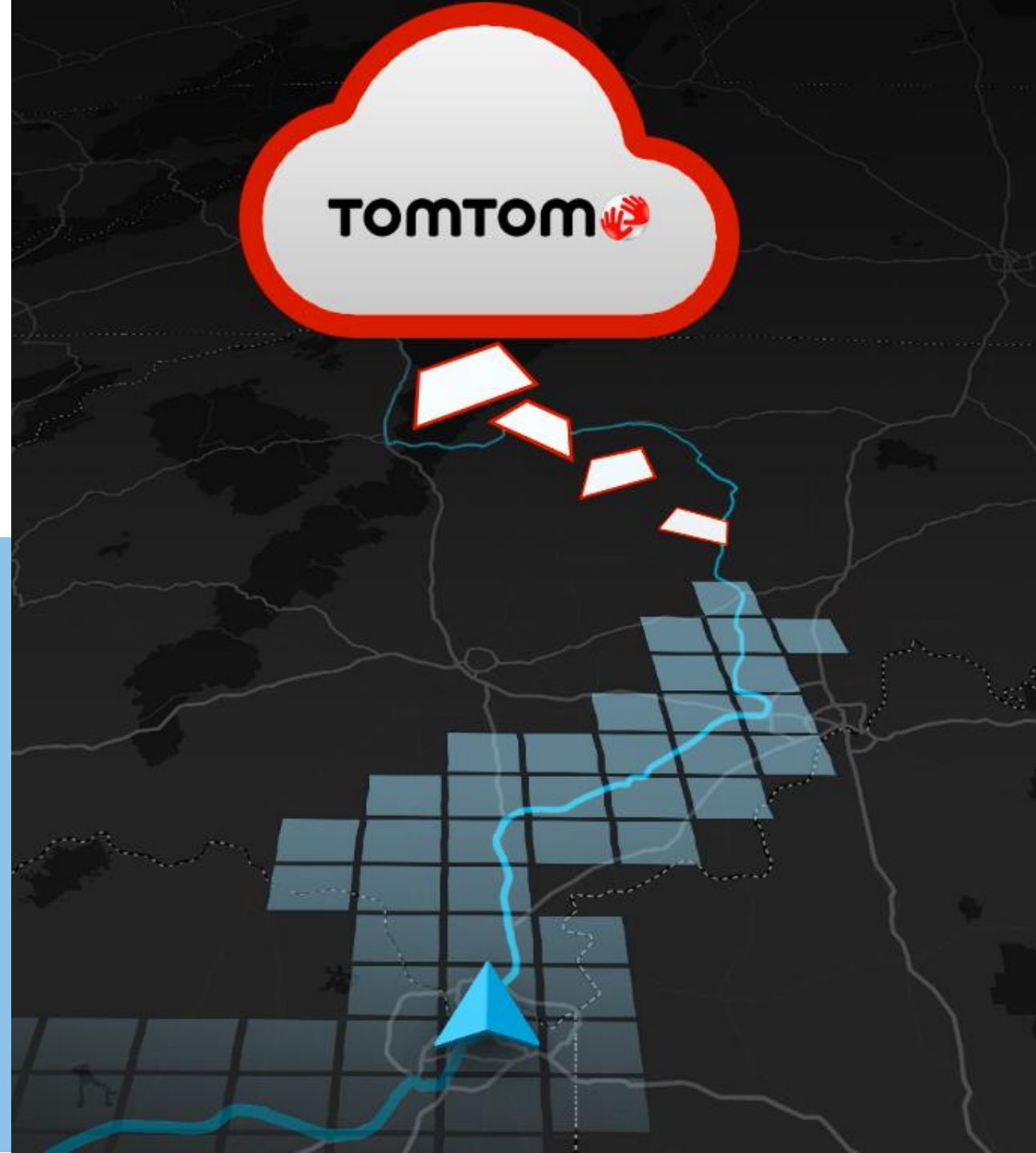
THE COMBINATION OF
2 DGPS ANTENNAS,
INERTIAL SENSORS AND
THE ODOMETER ENSURE
**HIGHLY
ACCURATE
POSITIONING**



3+
MILLION KM
DRIVEN BY MOBILE
MAPPING VEHICLES
EACH YEAR

AutoStream: Innovative map delivery for automated driving

- AutoStream service streams map data in tiles and layers along route or MPP
- AutoStream onboard client integrates with Vehicle Horizon
- Reduces complexity and development time thanks to smart on-board client software
- Minimize data consumption with onboard cache



Crowdsourced sensor data is key for map maintenance

Data from onboard sensors is key for keeping the HD Map up-to-date.

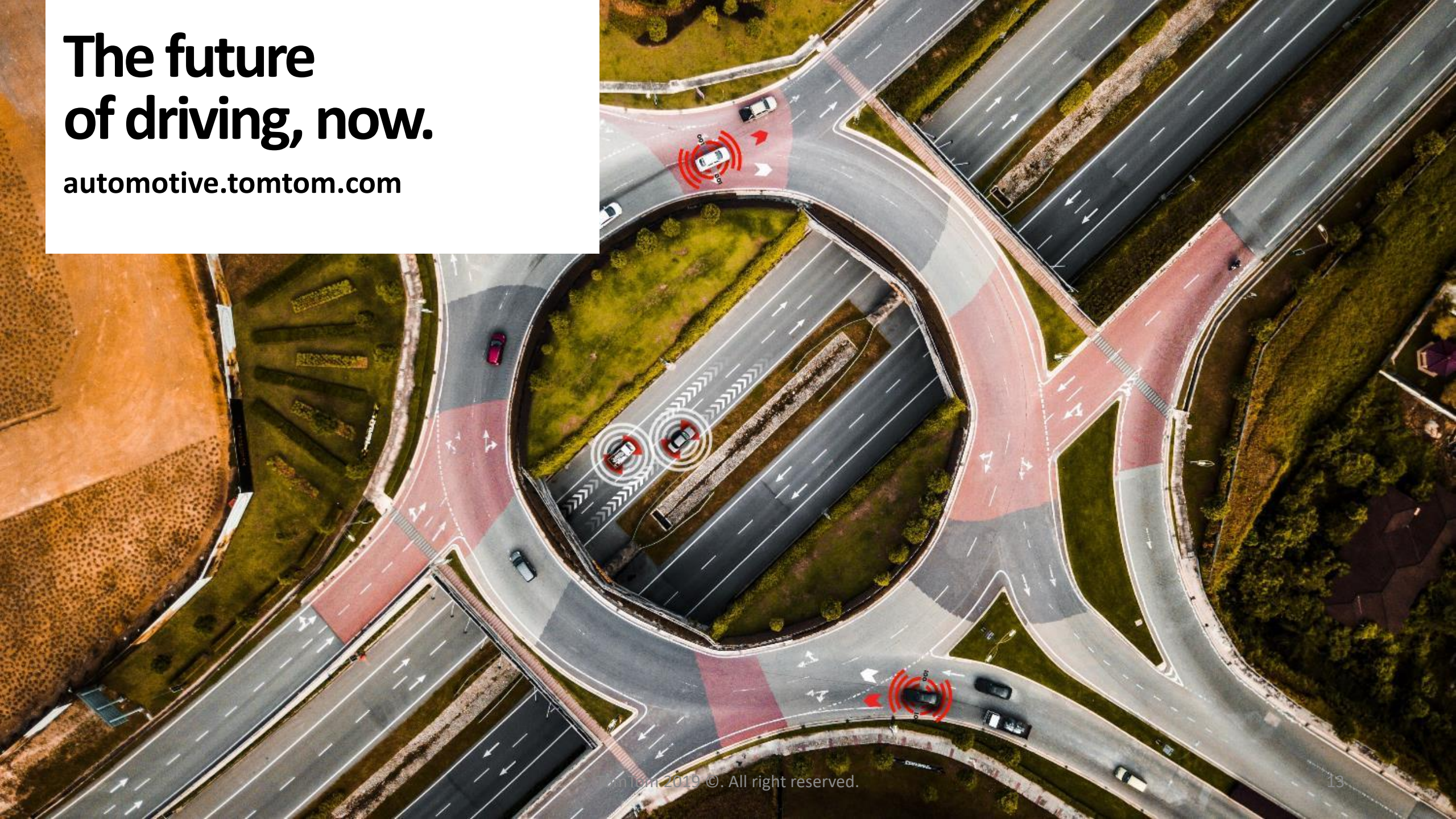
For this purpose, TomTom defined Roadagrams: a format for compressed snippets of camera data that can be used as input to update the HD Map.

TomTom will intake Roadagrams generated by vehicles on the road and use them as input for HD Map maintenance.



The future of driving, now.

automotive.tomtom.com



Michigan Connected and Automated Vehicle Working Group

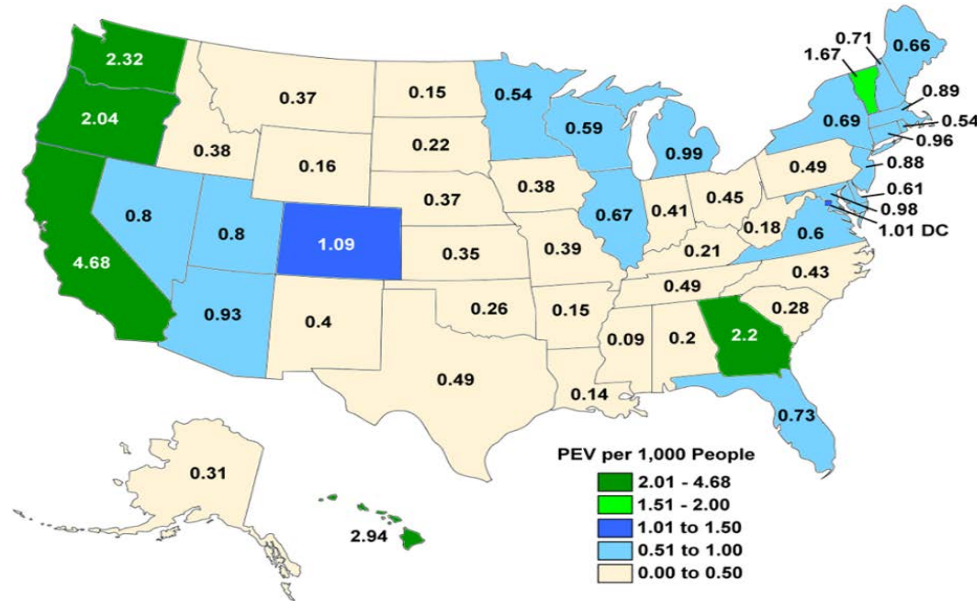
Consumers Energy Electric Vehicle Strategy July 23, 2019

Scott A Weber
Director of Alternative
Energy Solutions
Renewable Energy & Electric Vehicles



Michigan can take a leadership role in defining a scalable model for EV infrastructure and adoption

PEV REGISTRATIONS PER 1,000 PEOPLE BY STATE, 2015



2019
1.5 EV per
1000 people

OUR VISION

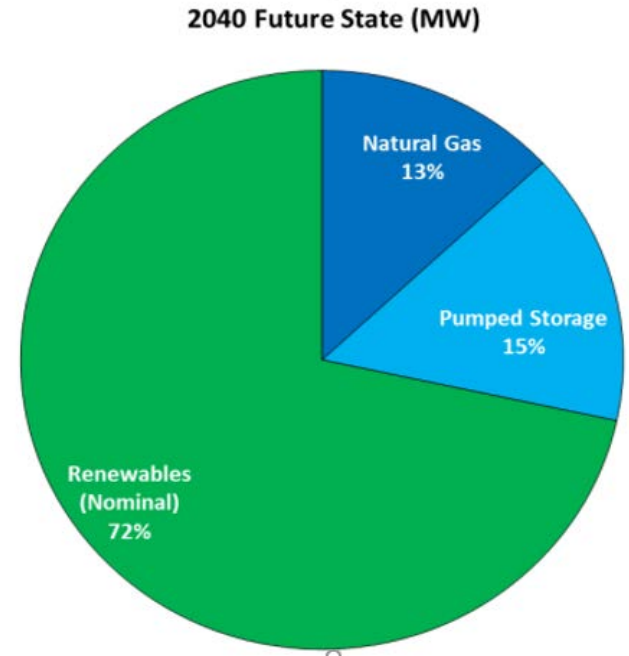
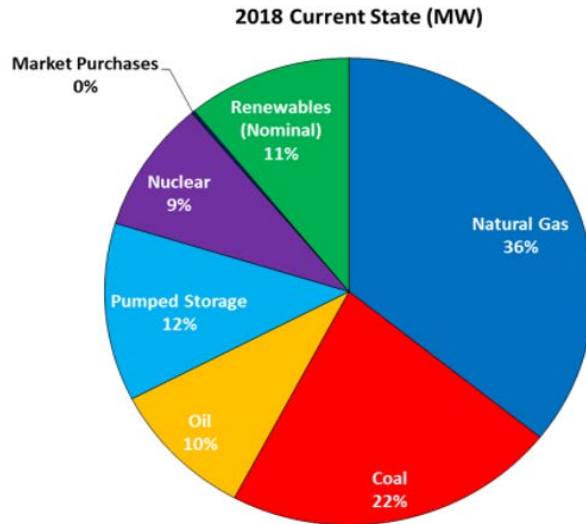
Michigan leverages its energy and automotive legacies to develop customer-focused solutions for EV infrastructure that can be replicated across the U.S.

Consumers Energy Starts New Era for Renewable Energy in Michigan with Approval of Clean Energy Plan

Jackson, Mich. Friday, June 07, 2019

A New Energy Future for Michigan

TRANSITION TO ZERO COAL
MORE DEMAND REDUCTION
MORE RENEWABLE ENERGY



Affordable, Reliable, and Environmentally Responsible

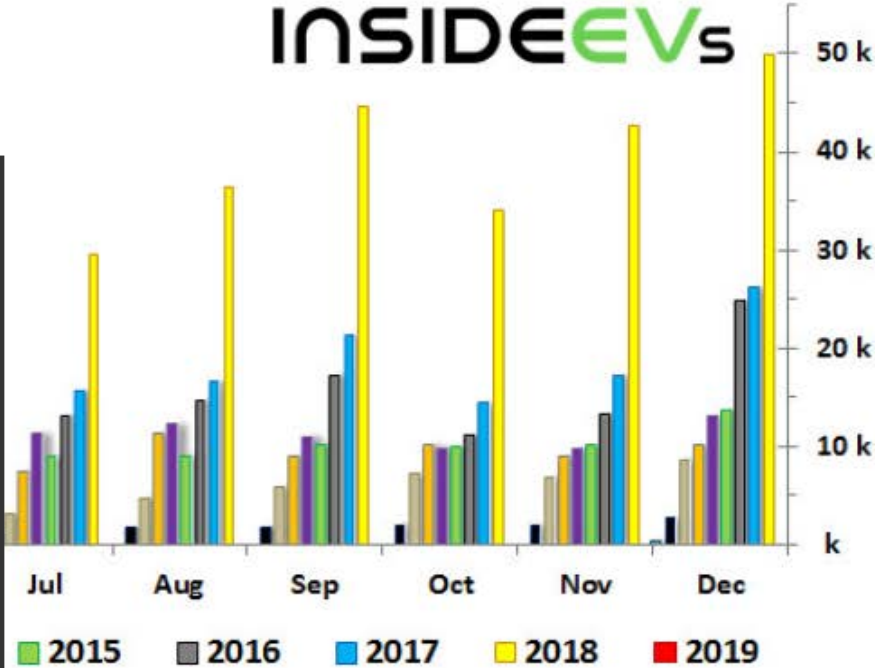
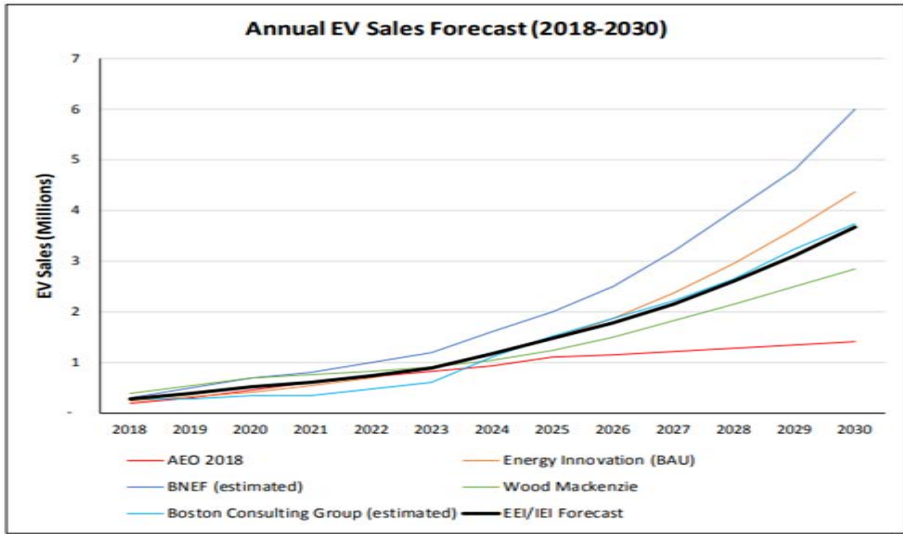
Forecast and Actual PEV Sales

U.S. Plug-In Car Sales



INSIDE EVs

Figure 4. EEI/IEI Annual EV Sales Forecast Compared to Selected Forecasts



Three-year program to make it easier for electric vehicles (EV) owners to charge their EVs, and to ensure the electric grid is prepared to capture the benefits for our customers from the growing EV market

Includes:

- **Rate options** to help EV owners maximize the value of their vehicle by charging off peak and at night
- **Education campaign** to build awareness and understanding



\$400 for customers who install an approved Level 2 Charger at their residence, and sign up for our EV rate. *Additional savings available to low-income customers.*



Up to \$5,000 for commercial customers who install an approved Level 2 Charger in public location. *Total number of rebates limited.*



Up to \$70,000 for commercial customers who install an approved DC Fast Charger in public location. *Total number of rebates limited.*



Charging Options



Explore Your Options

PowerMIDrive Rebates



Explore Available Rebates

Rates and Plans



Explore Your Options



How much can you save with your next car?

Easily compare your favorite car models based on fuel efficiency, available incentives and total cost of ownership.

56

LEXUS
2019 IS 300



TESLA
2019 Model 3 Standard Range
Battery Plus RWD

97



CLEARCOST

\$53,789

\$41,188

BREAKDOWN

| | | | |
|------------------|------------|--------------------------------------|-----------|
| MSRP | \$38,560 | MSRP | \$38,990 |
| FUEL COST (5YRS) | + \$15,229 | ELECTRICITY COST (5YRS) | + \$4,073 |
| | | UP TO \$1,875 IN A FEDERAL INCENTIVE | - \$1,875 |

Enhanced Website Options

Electrification Strategy

EARLY UTILITY ROLE

Utilities have a role early in the customer journey, as a trusted voice and valuable resource for data and in-home touchpoints

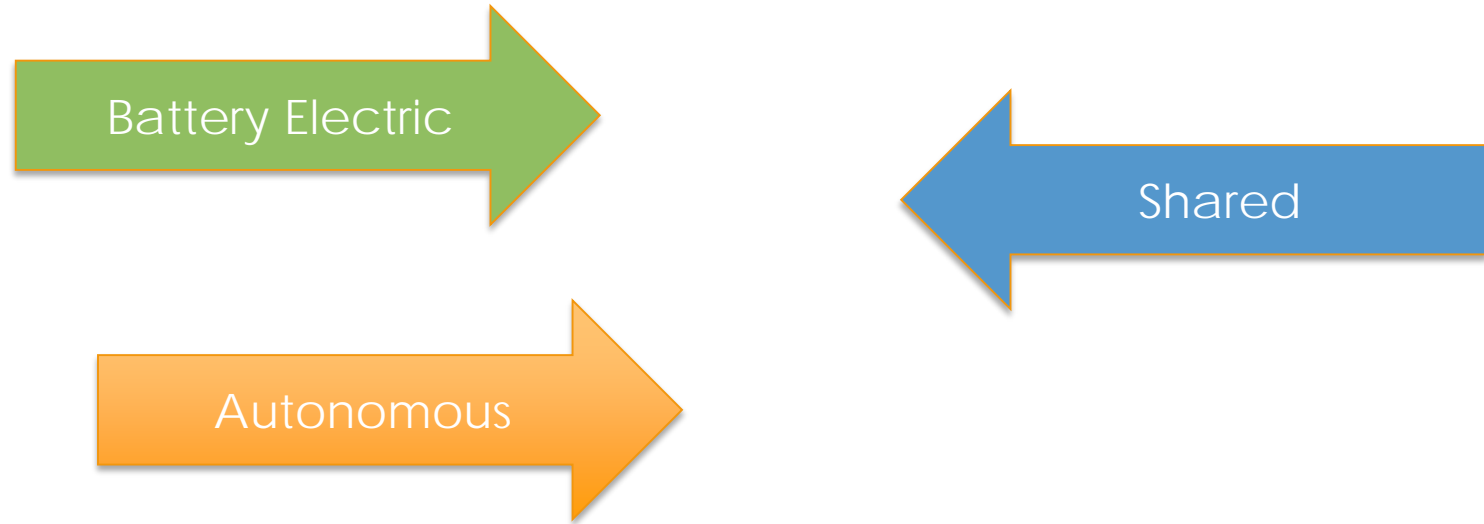
ENABLING ADOPTION

Setting the foundational structure for Plugin vehicles, provide insight & education & positive customer experience

OBSERVE ADJUST & REACT

Modify programs to support adoption and influence behaviors that will provide positive outcomes for all customers

Maintain a pulse on market trends to define the leading drivers and influence of emerging mobility technologies and services.



Thank you

Scott A Weber
Director of Alternative
Energy Solutions
Renewable Energy & Electric Vehicles